

**IN THE CLAIMS:**

Please amend the heading of the claims as follows:

~~CLAIMS (as amended on October 19, 2004)~~ WHAT IS CLAIMED IS:

Please amend the claims as follows:

Claim 1 (Currently Amended): A method of preventing a mine vehicle from colliding, the mine vehicle  $[(1)]$  comprising at least: a movable carrier  $[(2)]$  that may be driven in a first movement direction  $[(A)]$  and in a second movement direction  $[(B)]$ , at least one scanner  $[(13, 14)]$ , and a control system including at least a first control unit  $[(4)]$  arranged on the carrier  $[(2)]$ ; the method comprising:

determining for the mine vehicle  $[(1)]$  at least one safe area ~~(15a, 15b, 15c)~~ provided within an area between minimum distances  $[(16)]$  and maximum distances  $[(17)]$  determined with respect to the vehicle  $[(1)]$ ;

scanning the environment in front of the vehicle  $[(1)]$  when driving the vehicle  $[(1)]$  in one movement direction  $[(A, B)]$ ;

carrying out a first collision examination wherein the safe area  $[(15a)]$  in front of the vehicle  $[(1)]$  is monitored, and issuing a collision warning message if an obstacle is detected within the safe area  $[(15a)]$ , ~~characterized by~~

determining also at least one sideward  $[(C)]$  safe area  $[(15b)]$  for the vehicle  $[(1)]$ , determining an obstacle-free route  $[(24)]$  on the basis of scanning results, and determining points in a sideward  $[(C)]$  direction of the vehicle  $[(1)]$  to restrict the route  $[(24)]$ ;

forming memory points  $[(21)]$  on the basis of coordinates of the points restricting the route  $[(24)]$ , and storing the memory points  $[(21)]$  in the control system $[[;]]$

and carrying out a second collision examination wherein at least one sideward safe area ~~[[15b]]~~ of the vehicle is monitored, and issuing a collision warning message if even one of the memory points ~~[[21]]~~ resides within the safe area ~~[[15b]]~~ being monitored.

Claim 2 (Currently Amended): A method as claimed in claim 1, ~~characterized by~~  
comprising

simulating in advance, on the basis of position and control data, the path of movement of at least one part of the vehicle ~~[[1]]~~ in the control system,

carrying out the second collision examination by taking into account the path of movement obtained by simulation,

and adjusting, on the basis of the second collision examination, steering movements of the vehicle ~~[[1]]~~ in order to avoid overstepping the sideward safe area ~~[[15b]]~~.

Claim 3 (Currently Amended): A method as claimed in claim 1 ~~or 2~~, ~~characterized by~~  
comprising storing substantially continuously the memory points ~~[[21]]~~ in a ring buffer provided in the control system,

and updating for the second collision examination the memory points ~~[[21]]~~ in a ring memory with respect to the movement of the vehicle ~~[[1]]~~.

Claim 4 (Currently Amended): A method as claimed in ~~any one of the preceding claims~~  
claim 1, ~~characterized by~~ comprising

controlling the vehicle ~~[[1]]~~ unmannedly,

and utilizing for such control a data transmission connection ~~[[6]]~~ provided between the first control unit ~~[[4]]~~ residing on the carrier ~~[[2]]~~ of the vehicle ~~[[1]]~~ and a second, external control unit ~~[[7]]~~.

Claim 5 (Currently Amended): A method as claimed in ~~any one of the preceding claims~~  
claim 1, characterized by comprising

updating dimensions of at least one safe area ~~(15a to 15e)~~ on the basis of the location of  
the mine vehicle ~~[(1)]~~.

Claim 6 (Currently Amended): A mine vehicle comprising at least:

a movable carrier ~~[(2)]~~ that may be driven in a first movement direction ~~[(A)]~~ and in a  
second movement direction ~~[(B)]~~,

at least one scanner ~~(13, 14)~~,

~~and~~ a control system including at least a first control unit ~~[(4)]~~ arranged on the carrier  
~~[(2)]~~;

and wherein

at least one scanner is configured to scan the environment in front of the vehicle ~~[(1)]~~ in  
order to detect obstacles ~~(10, 18)~~;

at least one safe area ~~(15a to 15e)~~ defined by minimum distances ~~[(16)]~~ and maximum  
distances ~~[(17)]~~ determined with respect to the vehicle ~~[(1)]~~ is determined in the control  
system;

and which control system is configured to monitor scanning results and to issue a  
collision warning message if an obstacle is detected within the safe area ~~[(15a)]~~ in front of the  
vehicle ~~[(1)]~~, ~~characterized in that~~

and wherein

in the control system, at least one safe area ~~[(15b)]~~ in a sideward ~~[(C)]~~ direction of the  
vehicle ~~[(1)]~~ is further determined,

the control system allows several memory points  $[(21)]$  including their position information to be stored therein the memory points defining sideward points of the route and based on the scanning results,

and the control system is configured to monitor at least one sideward  $[(C)]$  safe area  $[(15b)]$  of the vehicle  $[(1)]$  and to issue a collision warning message if even one of the memory points  $[(21)]$  resides within the safe area  $[(15b)]$  being monitored.

Claim 7 (Currently Amended): A mine vehicle as claimed in claim 6, ~~characterized in that~~ wherein

the mine vehicle  $[(1)]$  comprises a first laser scanner  $[(13)]$  directed in a first movement direction  $[(A)]$  and a second laser scanner  $[(14)]$  directed in a second movement direction  $[(B)]$ ,

and ~~that~~ wherein each movement direction  $[(A, B)]$  is provided with a safe area (~~15a, 15b~~) of its own.

Claim 8 (Currently Amended): A mine vehicle as claimed in claim 6 ~~or 7, characterized in that~~ wherein

the minimum distances  $[(16)]$  of the safe area (~~15a, 15b, 15c~~) are determined according to the external shape and structure of the mine vehicle  $[(1)]$ .

Claim 9 (Currently Amended): A mine vehicle as claimed in ~~any one of claims 6 to 8~~ claim 6, characterized in that wherein

the mine vehicle  $[(1)]$  is unmanned,

and ~~that~~ wherein the first control unit  $[(4)]$  is through a data transmission connection  $[(6)]$  connected to a second, external control unit  $[(7)]$  in order to transfer control data between the control units  $[(4, 7)]$ .

Claim 10 (Currently Amended): A mine vehicle as claimed in ~~any one of claims 6 to 9~~  
~~claim 6, characterized in that~~ wherein the control system is configured to update at least one safe  
area ~~(15a to 15e)~~ on the basis of the location of the mine vehicle ~~[(1)]~~.